Reasoning about connectivity without paths

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Dip. Matematica e Geoscienze — DMI



Reasoning about connectivity without paths¹

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¹Work partially funded by: INdAM/GNCS 2013, FRA-UniTS 2012 PUMA



EVERY CONNECTED GRAPH HAS NON-CUT VERTICES



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EVERY CONNECTED GRAPH HAS NON-CUT VERTICES





More generally:

'Every connected (finite) hyper graph has at least one vertex whose removal does not disrupt connectivity'

(IDEAL) ITINERARY OF THIS TALK

I Connectivity and non-cut vertices

II Applications (one in particular...)

III The proof assistant Ref

IV Our proof-verification experiment http://www2.units.it/eomodeo/NonCutVertices.html http://aetnanova.units.it/scenarios/NonCutVertices/ Connectivity plays a crucial role in many fields.

- Es. The number of connected components of a graph
 - is a topological invariant;
 - corresponds to the multiplicity of the eigenvalue 0 in its Laplacian;
 - is related to the number of its claw-free subgraphs [CPR07].

. Large scale proof-verification efforts [Wie07, SCO11] must formally investigate this notion.

Example



Example



The edges of G belong to G.

Example



The
$$\left\{ \begin{array}{c} \text{vertices} \\ \text{or} \\ \text{nodes} \end{array} \right\}$$
 of *G* belong to $\{v : e \in G, v \in e\}$.

Example



In a graph, the edges have cardinality 2.

OUR FORMAL DEFINITION OF CONNECTIVITY

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Def. Conn(G) $(p \subseteq G \mid nodes(p) \cap nodes(G \setminus p) = \emptyset \subseteq \{\emptyset, G\} \&$ HGraph(G)

OUR FORMAL DEFINITION OF CONNECTIVITY



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- Def. CardAtLeast2(E) \leftrightarrow_{Def} E \subseteq {**arb**(E)}
- Def. nodes(G) $=_{Def} \bigcup G$
- $\begin{array}{lll} \text{Def. Conn}(G) & \longleftrightarrow_{\text{Def}} & \{p \subseteq G \mid nodes(p) \cap nodes(G \setminus p) = \emptyset\} = \{\emptyset, G\} \And \\ & \text{HGraph}(G) \end{array}$



EXISTENCE OF NON-CUT VERTICES

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 $\mathsf{Thm.} \ \mathsf{Conn}(\mathsf{G}) \And \mathsf{G} \not\subseteq \{\mathbf{arb}(\mathsf{G})\} \to \big\langle \exists \mathsf{v} \in \mathsf{nodes}(\mathsf{G}) \mid \mathsf{Non}\mathsf{Cut}(\mathsf{G},\mathsf{v}) \big\rangle$

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Def. NonCut(G, V) \leftrightarrow_{Def} Conn(rmv(G, V)) & lost(G, V) = \emptyset

Thm. Conn(G) & G $\not\subseteq$ {**arb**(G)} \rightarrow $\langle \exists v \in \mathsf{nodes}(G) | \mathsf{NonCut}(G, v) \rangle$

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Thm. Conn(G) & G $\not\subseteq$ {**arb**(G)} \rightarrow $\langle \exists v \in \mathsf{nodes}(G) | \mathsf{NonCut}(G, v) \rangle$

How can we:

- walk along an infinite acyclic path?
- visit all vertices of a finite acyclic path?













EXAMPLE



Example



This amounts to repeatedly picking and removing a non-cut vertex (the *only one*, in this case) from a graph (*infinite* in this case)

EXAMPLE



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Why such a silly example ?



Where does the difference between \mathbb{N} and $\mathbb{N} \cup \{\mathbb{N}, \mathbb{N} \cup \{\mathbb{N}\}\}$ lie ?






Example

We can get a spanning tree for a connected nonnull graph by:

- Picking & removing a non-cut vertex from a connected graph
- I recursively getting a spanning tree for the resulting graph
- restoring the removed vertex, along with one of the edges incident to it

Example

We can get a spanning tree for a connected nonnull graph by:

• Picking & removing a non-cut vertex from a connected graph

- I recursively getting a spanning tree for the resulting graph
- restoring the removed vertex, along with one of the edges incident to it

• In the base case , the spanning tree consists of the (sole) edge

Example



THIS EXAMPLE IS PARADIGMATIC:

Inductive proofs on connected graphs usually follow this pattern

DIRECT MOTIVATING APPLICATION

An achievement, but also a pending proof obligation:

DIRECT MOTIVATING APPLICATION

An achievement, but also a pending proof obligation:

Set Graphs. III. Proof Pearl: Claw-Free Graphs Mirrored into Transitive Hereditarily Finite Sets

Eugenio G. Omodeo & Alexandru I. Tomescu

Journal of Automated Reasoning

ISSN 0168-7433 Volume 52 Number 1

J Autom Reasoning (2014) 52:1-29 DOI 10.1007/s10817-012-9272-3 Journal of Automated Reasoning



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Two fully formal reconstructions of results on *connected claw-free graphs* have been achieved by means of Ref.







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Set graphs. III. Proof Pearl: Claw-free graphs mirrored into transitive hereditarily finite sets.

J. Autom. Reason., 52(1), pp.1-29, 2014. Cf. http://www2.units.it/eomodeo/ClawFreeness.html



E. G. Omodeo and A. I. Tomescu.

Appendix: Claw-free graphs as sets.

In: M. Davis, E. Schonberg (eds.) From Linear Operators to Computational Biology: Essays in Memory of Jacob T. Schwartz, pp. 131–167, Springer, 2012. Two fully formal reconstructions of results on *connected claw-free graphs* have been achieved by means of Ref.

E. G. Omodeo and A. I. Tomescu.
Set graphs. V. On representing graphs as membership digraphs.
To appear on J. Log. Comput.
Cf. http://www2.units.it/eomodeo/GraphsViaMembership.html

E. G. Omodeo and A. I. Tomescu. Set graphs. III. Proof Pearl: Claw-free graphs mirrored into transitive hereditarily finite sets.

J. Autom. Reason., 52(1), pp.1-29, 2014. Cf. http://www2.units.it/eomodeo/ClawFreeness.html



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A graph (V, E) is said to be <u>claw-free</u> if none of its subgraphs induced by 4 vertices has the shape of a 'Y'

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FIGURE: Forbidden claw $K_{1,3}$

A graph (V, E) is said to be <u>claw-free</u> if none of its subgraphs induced by 4 vertices has the shape of a 'Y'



FIGURE: Worse than a claw

A graph (V, E) is said to be <u>claw-free</u> if none of its subgraphs induced by 4 vertices has the shape of a 'Y'



FIGURE: A claw-free graph

"Every connected claw-free graph admits a perfect matching and has a Hamiltonian cycle in its square". (1970s / 1980s)



"Every connected claw-free graph admits a perfect matching and has a Hamiltonian cycle in its square". (1970s / 1980s)



Also: Each connected claw-free graph has a vertex-pancyclic square

Martin Milanič and A. I. Tomescu found new, simpler proofs of the results just mentioned via a theorem about the representation of edges as (directed!) membership arcs.









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M. Milanič and A. I. Tomescu.

Set graphs. I. Hereditarily finite sets and extensional acyclic orientations. *Discrete Applied Mathematics*, 161(4-5):677–690, 2013.



A. I. Tomescu.

A simpler proof for vertex-pancyclicity of squares of connected claw-free graphs. *Discrete Mathematics*, 312(15):2388–2391, 2012.





ÆTNANOVA aka Referee:

Cf. [SCO11]

-	P9
	OOO AetnaNova Preliminary - W ×
	← → C
	Share: 🗹 Verify: 1109 GO Me: Gue Pretty: 108,109
-	Book Full Common Scenario Verifier Help
	More Files: Choose File GraphsViaMembership.tex Choose File No file chosen Choose File No file
	Scenario extension:
	Put the final piece of scenario here.

(On-line worksheet)

INTERACTION WITH OUR PROOF-VERIFIER



```
--BEGIN HERE
Def pow: [Family of all subsets of a given set] pow(S) := { x : x • jncin S }
Def trans: [Transitivity w.r.t. membership] Trans(T) := {y in T | y • nincin T} = 0
Theorem trans_1: [Peddicord's lemma] (Trans(T) & (S +incin T) & (S /= T)) +imp (0 /= (T-S) * pow(S)). Proof:
Suppose not(t0,s0) ==> AUTO
  Use def(pow(s0)) = = > AUTO
  Loc def ==> Stat1: a = arb(t0-s0)
  Use_def(Trans) ==> Stat2: ({y in t0 | y •nincin t0} = 0) & (a notin {z: z •incin s0})
  (a.a)-->Stat2(Stat1) ==> false
  Discharge ==> OED
Theorem trans_2: [Peddicord's lemma, main corollary] Trans(T) • imp (0 in T). Proof:
Suppose not(t0) ==> AUTO
  (t0,0)-->Ttrans 1 ==> Stat1: 0 /= t0 * pow(0)
  Use def(pow(0)) ==> AUTO
  z \rightarrow Stat1 = Stat2: (z in { x : x • incin 0 }) & (z in t0)
  z1-->Stat2 ==> false
  Discharge ==> QED
--END HERE
```

INPUT

INTERACTION WITH OUR PROOF-VERIFIER (OUTPUT

Misc. Init. Output 🔘 Good Pfs. 🔘 Bad 🕢

I & R & S & R & P & G & S & G &

	Thm. No.	Thm. Name	Line No.	F/A	Line	
	2	Ttrans_2	2	F	(t0,0)>Ttrans_1 ==> Stat1: 0 /= t0 * pow(0)	
					Attempt to derive MLS contradiction has failed	

++++++ Ttrans_2#2 -- 26 ****** Error verifying step: 2 of theorem Ttrans_2

(t0,0)-->Ttrans 1 ==> Stat1: 0 /= t0 * pow(0)

Attempt to derive MLS contradiction has failed

reduced blobbed statement was: $BLB_1 \& \neg \{\} \in T_0 \& \neg \{\} \neq T_0 \cap BLB_2 \& (BLB_1 \& \{\} \neq T_0 \rightarrow T$

INTERACTION WITH OUR PROOF-VERIFIER (OUTPUT

Misc. Init. Output 🔘 Good Pfs. 🔘

Pfs. 🔵 🛛 Bad 💿

	Thm. No.	Thm. Name	Line No.	F/A	Line	
۰	2	Ttrans_2	2	F	(t0,0)>Ttrans_1 ==> Stat1: 0 /= t0 * pow(0)	
					Attempt to derive MLS contradiction has failed	

+++++++ Ttrans_2#2 -- 26 ****** Error verifying step: 2 of theorem Ttrans_2

(t0,0)-->Ttrans_1 ==> Stat1: 0 /= t0 * pow(0)

Attempt to derive MLS contradiction has failed

Misc. Init. Output 🔵 Good Pfs. 💿

reduced blobbed statement was: $BLB_{-1} \& \neg \{\} \in T_0 \& \neg \{\} \neq T_0 \cap BLB_{-2} \& (BLB_{-1} \& \{\} \neq T_0 \rightarrow T_0 \rightarrow$

Bad 🔾

Thm. No. Thm. Name Time Details						
1	Ttrans_1	#6: t20	Z4: 7	S5: 8		
2	Ttrans_2					

g 2 g 🕄 🚖 8 g 🦻 😔 🐨 👰 😭

DEFINITION:

SHORTHAND

-- After the celebrated paper Sur les ensembles fini (Tarski, 1924)

 $\mathsf{Def.} \ \mathsf{Finite}(\mathsf{F}) \quad \longleftrightarrow_{\mathsf{Def}} \ \left\langle \forall \mathsf{g} \in \mathcal{P}(\mathcal{P}(\mathsf{F})) \backslash \{ \emptyset \}, \ \exists \mathsf{m} \mid \mathsf{g} \cap \mathcal{P}(\mathsf{m}) = \{ \mathsf{m} \} \right\rangle$

DEFINITION:

$(\in$ -recursion here!

-- "The cardinality of S exceeds M"

 $\mathsf{Def.}\ \mathsf{Exc}(\mathsf{S},\mathsf{M}) \ \leftrightarrow_{\mathsf{Def}} \ \mathsf{S} \neq \emptyset \And \big\{ p \in \mathsf{M} \mid \neg \mathsf{Exc}\big(\mathsf{S} \setminus \{\mathbf{arb}(\mathsf{S})\}, p\big) \big\} = \emptyset$

THEOREM AND PROOF:

(Monotonicity of finitude

Thm fin₀. $Y \supseteq X \& Finite(Y) \rightarrow Finite(X)$. Proof: Suppose_not(y₀, x₀) \implies y₀ \supseteq x₀ & Finite(y₀) $\& \neg Finite(x_0)$ $\langle y_0, x_0 \rangle \hookrightarrow Tpow_1 \implies Py_0 \supseteq Px_0$ Use_def(Finite) \implies Stat1: $\neg \langle \forall g \in P(Px_0) \setminus \{\emptyset\}, \exists m \mid g \cap Pm = \{m\} \rangle$ $g \cap Pm = \{m\} \rangle \& \langle \forall g' \in P(Py_0) \setminus \{\emptyset\}, \exists m \mid g' \cap Pm = \{m\} \rangle$ $\langle Py_0, Px_0 \rangle \hookrightarrow Tpow_1 \implies P(Py_0) \supseteq P(Px_0)$ $\langle g_0, g_0 \rangle \hookrightarrow Stat1(Stat1*) \implies \neg \langle \exists m \mid g_0 \cap Pm = \{m\} \rangle \&$ $\langle \exists m \mid g_0 \cap Pm = \{m\} \rangle$ Discharge \implies Qed

Theory finite_image $(s_0, g(X))$ Finite (s_0) End finite image

Enter_theory finite_image

: : : :

Enter_theory Set_theory

```
Theory finite_image (s<sub>0</sub>, g(X))
Finite(s<sub>0</sub>)
End finite image
```

Enter_theory finite_image

	•	•
	•	•
	•	•

Enter_theory Set_theory

Within a scenario, the discourse can momentarily digress into a 'Theory' that enforces certain local assumptions. At the end of the digression, the upper theory will be re-entered.

```
Theory finite_image (s_0, g(X))

Finite(s_0)

\Rightarrow

Finite(\{g(x) : x \in s_0\})

Finite image
```

As an outcome of the digression, the Theory will be able to instantiate new theorems

```
Theory finite_image (s_0, g(X))

Finite(s_0)

\implies (f_{\Theta})

Finite(\{g(x) : x \in s_0\})

f_{\Theta} \subseteq s_0 \& \langle \forall t \subseteq f_{\Theta} | g(t) = g(s_0) \leftrightarrow t = f_{\Theta} \rangle

End finite_image
```

As an outcome of the digression, the Theory will be able to instantiate new theorems: possibly involving new symbols, whose definition it encapsulates. The script-file containing our verified formal derivation of the existence of non-cut vertices in hypergraphs:

- comprises 13 definitions;
- proves 46 theorems (only two whose length exceeds 50 lines),
- organized in 3 Theorys.
- Its processing takes ca. 4 seconds;
- the overall number of proof lines is 905.

http://www2.units.it/eomodeo/NonCutVertices.html
http://aetnanova.units.it/scenarios/NonCutVertices/

ON THE HUMAN SIDE, such results disclose new insights by shedding light on a discipline from unusual angles

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This contribution closes a cycle of activities related to claw-free graphs...

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ON THE TECHNOLOGICAL SIDE, they enable the transfer of proof methods from one realm of mathematics to another.

This contribution closes a cycle of activities related to claw-free graphs... ...and paves the way to an extensive exploration on how to formalize hypergraphs.

THANK YOU FOR YOUR ATTENTION!


Jacob T. Schwartz, Domenico Cantone, and Eugenio G. Omodeo. Computational Logic and Set Theory – Applying formalized Logic to Analysis. Springer, 2011. Foreword by Martin Davis.

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