

An algebraic characterization of unary 2-way transducers

Christian Choffrut¹ and Bruno Guillon^{1,2}

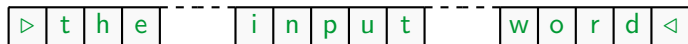
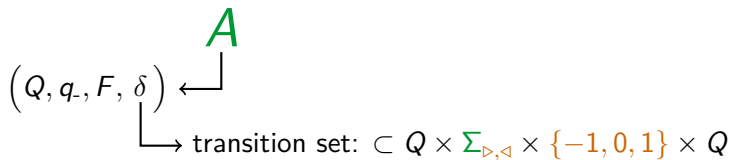
¹*LIAFA* - Université Paris-Diderot, Paris 7

²Dipartimento di Informatica - Università degli studi di Milano

Septembre 17, 2014
ICTCS - Perugia - 2014

work published in MFCS 2014

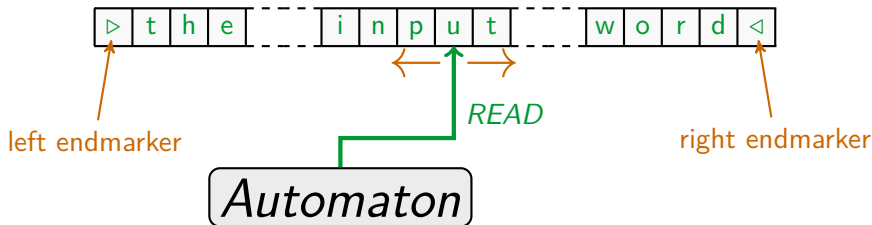
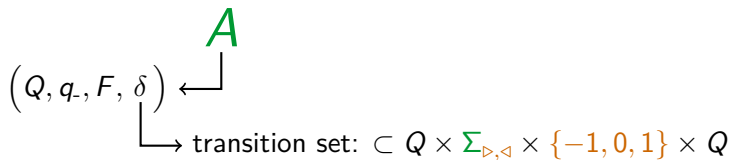
2-way automaton over Σ



Automaton

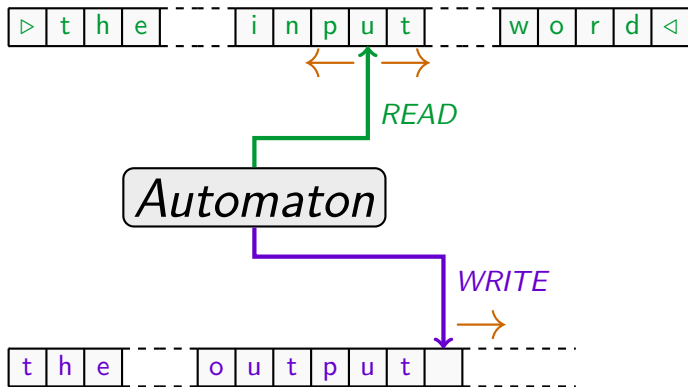
READ

2-way automaton over Σ

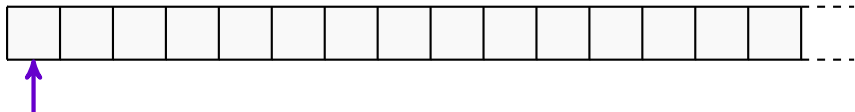
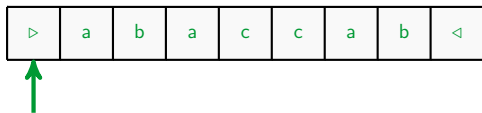


2-way transducer over Σ, Γ

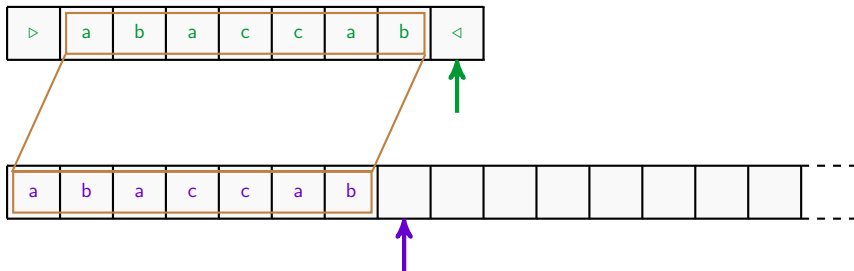
(Q, q_-, F, δ) \leftarrow (A, ϕ) \rightarrow production function: $\delta \rightarrow \text{Rat}(\Gamma^*)$



A simple example: $SQUARE = \{(w, ww) \mid w \in \Sigma^*\}$

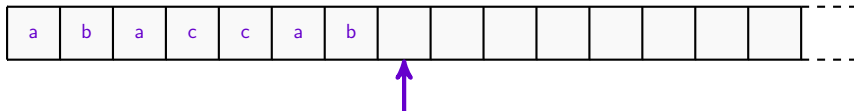
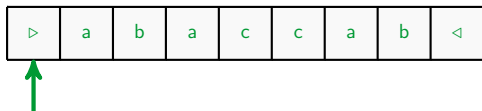


A simple example: $SQUARE = \{(w, ww) \mid w \in \Sigma^*\}$



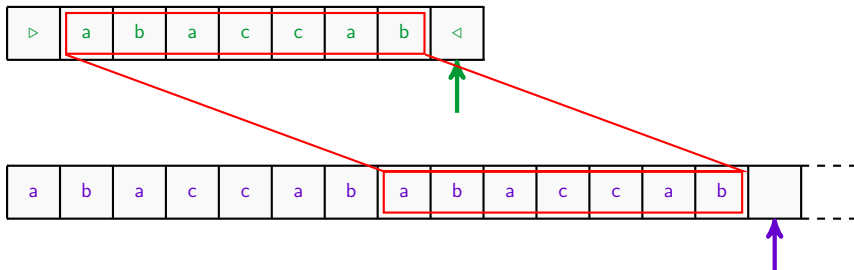
- ▶ copy the input word

A simple example: $SQUARE = \{(w, ww) \mid w \in \Sigma^*\}$



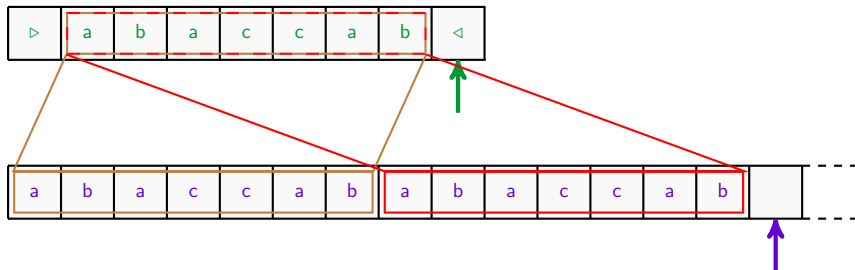
- ▶ copy the input word
- ▶ rewind the input tape

A simple example: $SQUARE = \{(w, ww) \mid w \in \Sigma^*\}$



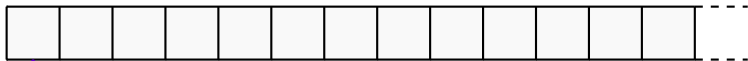
- ▶ copy the input word
- ▶ rewind the input tape
- ▶ append a copy of the input word

A simple example: $SQUARE = \{(w, ww) \mid w \in \Sigma^*\}$

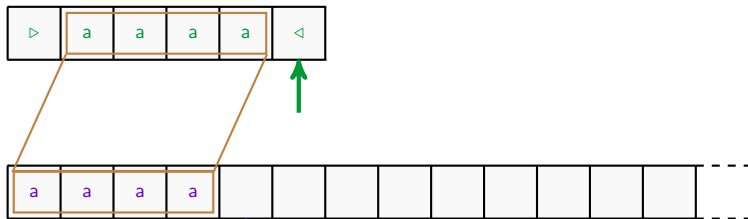


- ▶ copy the input word
- ▶ rewind the input tape
- ▶ append a copy of the input word

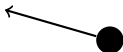
Another example: $UnaryMult = \{(a^n, a^{kn}) \mid k, n \in \mathbb{N}\}$



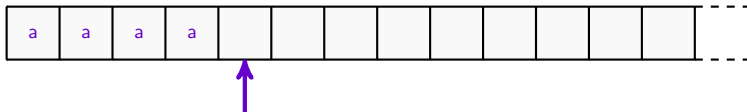
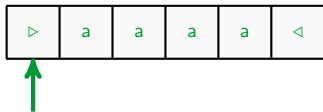
Another example: $UnaryMult = \{(a^n, a^{kn}) \mid k, n \in \mathbb{N}\}$



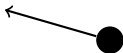
copy the input word



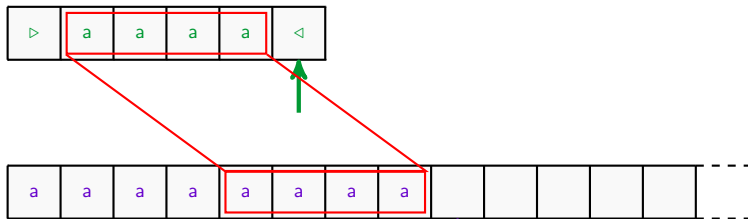
Another example: $UnaryMult = \{(a^n, a^{kn}) \mid k, n \in \mathbb{N}\}$



copy the input word \longrightarrow rewind the input tape



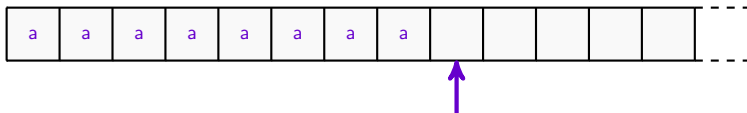
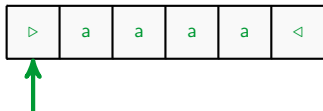
Another example: $UnaryMult = \{(a^n, a^{kn}) \mid k, n \in \mathbb{N}\}$



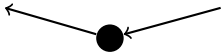
copy the input word \longrightarrow rewind the input tape



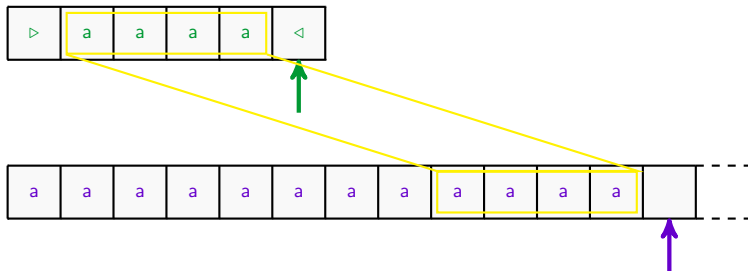
Another example: $UnaryMult = \{(a^n, a^{kn}) \mid k, n \in \mathbb{N}\}$



copy the input word \longrightarrow rewind the input tape



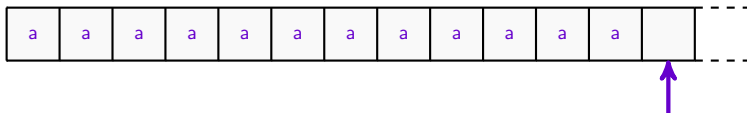
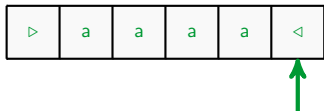
Another example: $UnaryMult = \{(a^n, a^{kn}) \mid k, n \in \mathbb{N}\}$



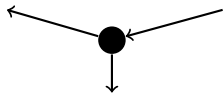
copy the input word \longrightarrow rewind the input tape



Another example: $UnaryMult = \{(a^n, a^{kn}) \mid k, n \in \mathbb{N}\}$

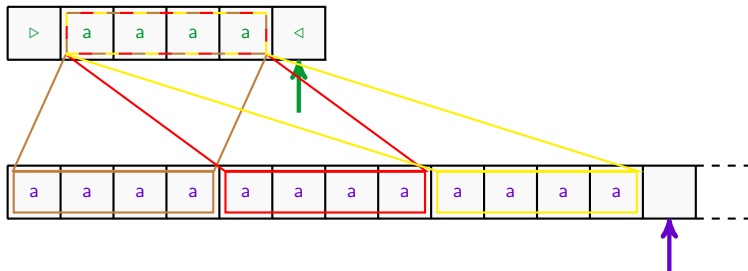


copy the input word \longrightarrow rewind the input tape

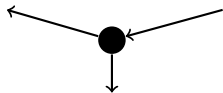


accept and halt with nondeterminism

Another example: $UnaryMult = \{(a^n, a^{kn}) \mid k, n \in \mathbb{N}\}$



copy the input word \longrightarrow rewind the input tape



accept and halt with nondeterminism

Rational operations

- ▶ Union

$$R_1 \cup R_2$$

- ▶ Componentwise concatenation

$$R_1 \cdot R_2 = \{(u_1 u_2, v_1 v_2) \mid (u_1, v_1) \in R_1 \text{ and } (u_2, v_2) \in R_2\}$$

- ▶ Kleene star

$$R^* = \{(u_1 u_2 \cdots u_k, v_1 v_2 \cdots v_k) \mid \forall i (u_i, v_i) \in R\}$$

Rational operations

- ▶ Union

$$R_1 \cup R_2$$

- ▶ Componentwise concatenation

$$R_1 \cdot R_2 = \{(u_1 u_2, v_1 v_2) \mid (u_1, v_1) \in R_1 \text{ and } (u_2, v_2) \in R_2\}$$

- ▶ Kleene star

$$R^* = \{(u_1 u_2 \cdots u_k, v_1 v_2 \cdots v_k) \mid \forall i (u_i, v_i) \in R\}$$

Definition ($Rat(\Sigma^* \times \Gamma^*)$)

The class of **rational relations** is the smallest class:

- ▶ that contains finite relations
- ▶ and which is closed under rational operations

Rational operations

- ▶ Union

$$R_1 \cup R_2$$

- ▶ Componentwise concatenation

$$R_1 \cdot R_2 = \{(u_1 u_2, v_1 v_2) \mid (u_1, v_1) \in R_1 \text{ and } (u_2, v_2) \in R_2\}$$

- ▶ Kleene star

$$R^* = \{(u_1 u_2 \cdots u_k, v_1 v_2 \cdots v_k) \mid \forall i (u_i, v_i) \in R\}$$

Definition ($Rat(\Sigma^* \times \Gamma^*)$)

The class of rational relations is the smallest class:

- ▶ that contains finite relations
- ▶ and which is closed under rational operations

Theorem (Elgot, Mezei - 1965)

1-way transducers \equiv *the class of rational relations*.

Hadamard operations

- ▶ H-product

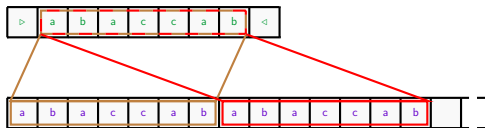
$$R_1 \otimes R_2 = \{(u, v_1 v_2) \mid (u, v_1) \in R_1 \text{ and } (u, v_2) \in R_2\}$$

Hadamard operations

- ▶ H-product

$$R_1 \textcircled{H} R_2 = \{(u, v_1 v_2) \mid (u, v_1) \in R_1 \text{ and } (u, v_2) \in R_2\}$$

Example: $SQUARE = \{(w, ww) \mid w \in \Sigma^*\} = Identity \textcircled{H} Identity$



- ▶ copy the input word
- ▶ rewind the input tape
- ▶ append a copy of the input word

Hadamard operations

- ▶ H-product

$$R_1 \oplus R_2 = \{(u, v_1 v_2) \mid (u, v_1) \in R_1 \text{ and } (u, v_2) \in R_2\}$$

- ▶ H-star

$$R^{H^*} = \{(u, v_1 v_2 \cdots v_k) \mid \forall i (u, v_i) \in R\}$$

Hadamard operations

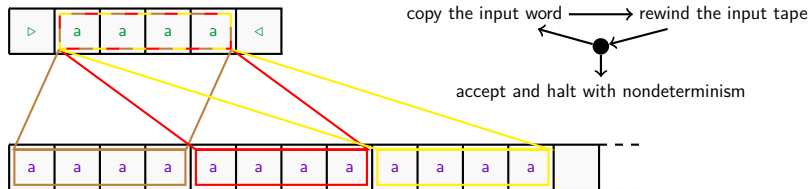
- ▶ H-product

$$R_1 \oplus R_2 = \{(u, v_1 v_2) \mid (u, v_1) \in R_1 \text{ and } (u, v_2) \in R_2\}$$

- ▶ H-star

$$R^{H^*} = \{(u, v_1 v_2 \cdots v_k) \mid \forall i (u, v_i) \in R\}$$

Example: $UnaryMult = \{(a^n, a^{kn}) \mid k, n \in \mathbb{N}\} = Identity^{H^*}$



H-Rat relations

Definition

A relation R is in $H\text{-Rat}(\Sigma^* \times \Gamma^*)$ if

$$R = \bigcup_{0 \leq i \leq n} A_i \oplus B_i^{\text{H}\star}$$

where for each i , A_i and B_i are rational relations.

Main result

When $\Sigma = \{a\}$ and $\Gamma = \{a\}$:

Theorem (Elgot, Mezei - 1965)

1-way transducers \equiv *the class of rational relations*.

Main result

When $\Sigma = \{a\}$ and $\Gamma = \{a\}$:

Theorem (This talk)

2-way transducers \equiv the class of H-Rat relations.

Main result

When $\Sigma = \{a\}$ and $\Gamma = \{a\}$:

Theorem (This talk)

2-way transducers \equiv the class of H-Rat relations.

Proof

- ▶ \supseteq : easy
- ▶ \subseteq : difficult part

Known results

- ▶ 2-way functional \equiv MSO definable functions

[Engelfriet, Hoogeboom - 2001]

Known results

- ▶ 2-way **functional** **=** **MSO definable functions**
[Engelfriet, Hoogeboom - 2001]
- ▶ 2-way **general** **incomparable** **MSO definable relations**
[Engelfriet, Hoogeboom - 2001]

Known results

- ▶ 2-way functional \equiv MSO definable functions
[Engelfriet, Hoogeboom - 2001]
- ▶ 2-way general incomparable MSO definable relations
[Engelfriet, Hoogeboom - 2001]
- ▶ 1-way simulation of 2-way functional transducer:
decidable and constructible [Filiot et al. - 2013]

Known results

- ▶ 2-way functional \equiv MSO definable functions
[Engelfriet, Hoogeboom - 2001]
- ▶ 2-way general incomparable MSO definable relations
[Engelfriet, Hoogeboom - 2001]
- ▶ 1-way simulation of 2-way functional transducer:
decidable and constructible
[Filiot et al. - 2013]

When $\Gamma = \{a\}$:

- ▶ 2-way unambiguous \rightarrow 1-way
[Anselmo - 1990]

Known results

- ▶ 2-way functional \equiv MSO definable functions
[Engelfriet, Hoogeboom - 2001]
- ▶ 2-way general incomparable MSO definable relations
[Engelfriet, Hoogeboom - 2001]
- ▶ 1-way simulation of 2-way functional transducer:
decidable and constructible [Filiot et al. - 2013]

When $\Gamma = \{a\}$:

- ▶ 2-way unambiguous \rightarrow 1-way
[Anselmo - 1990]
- ▶ 2-way unambiguous \equiv 2-way deterministic
[Carnino, Lombardy - 2014]

From *H-Rat* to 2-way transducers (unary case)

Property

The family of relations accepted by 2-way transducers is closed under \cup , \oplus and H^* .

From H -Rat to 2-way transducers (unary case)

Property

The family of relations accepted by 2-way transducers is closed under \cup , \textcircled{H} and H^* .

Proof.

- ▶ $R_1 \cup R_2$:
 - ▶ simulate T_1 or T_2



From H -Rat to 2-way transducers (unary case)

Property

The family of relations accepted by 2-way transducers is closed under \cup , \oplus and H^* .

Proof.

- ▶ $R_1 \cup R_2$:
 - ▶ simulate T_1 or T_2
- ▶ $R_1 \oplus R_2$:
 - ▶ simulate T_1
 - ▶ rewind the input tape
 - ▶ simulate T_2



From H -Rat to 2-way transducers (unary case)

Property

The family of relations accepted by 2-way transducers is closed under \cup , \oplus and H^* .

Proof.

▶ $R_1 \cup R_2$:

- ▶ simulate T_1 or T_2

▶ $R_1 \oplus R_2$:

- ▶ simulate T_1
- ▶ rewind the input tape
- ▶ simulate T_2

▶ R^{H^*} :

- ▶ repeat an arbitrary number of times:
 - ▶ simulate T
 - ▶ rewind the input tape
- ▶ reach the right endmarker and accept



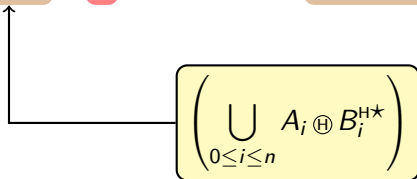
From *H-Rat* to 2-way transducers (unary case)

Property

The family of relations accepted by 2-way transducers is closed under \cup , \oplus and H^* .

Corollary

H-Rat \subseteq accepted by 2-way transducers



From 2-way transducers to *H-Rat* (unary case)

A first ingredient, a preliminary result:

Lemma

With arbitrary Σ and $\Gamma = \{a\}$:

H-Rat is closed under \cup , \oplus and H^* .

Proof.

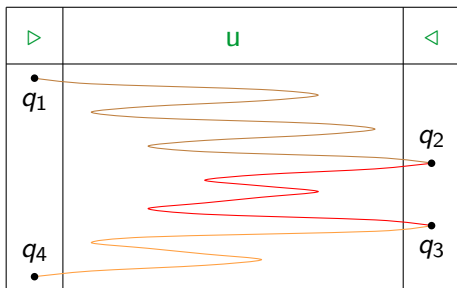
Tedious formal computations. . .



From 2-way transducers to *H-Rat* (unary case)

We fix a transducer \mathcal{T} .

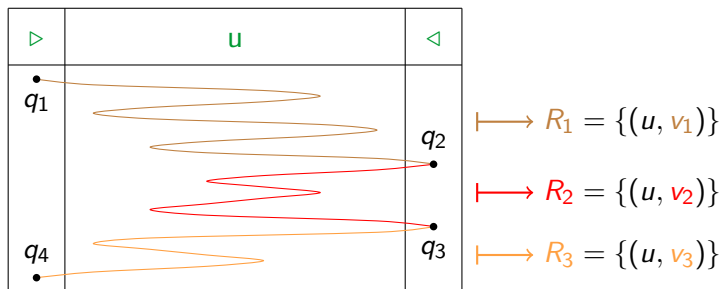
- ▶ Consider border to border run segments;



From 2-way transducers to *H-Rat* (unary case)

We fix a transducer \mathcal{T} .

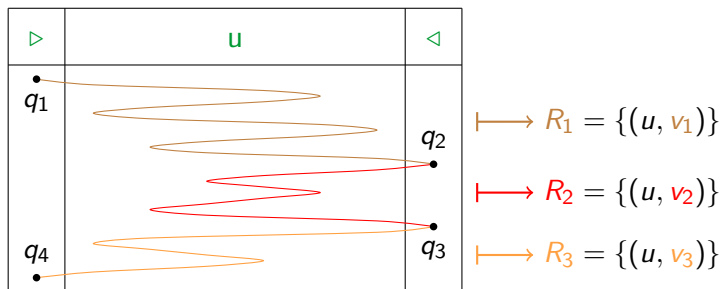
- ▶ Consider border to border run segments;



From 2-way transducers to *H-Rat* (unary case)

We fix a transducer \mathcal{T} .

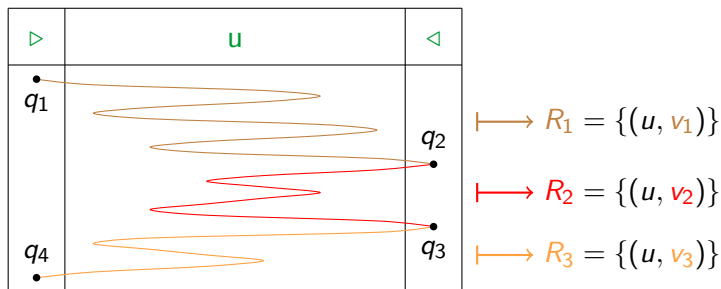
- ▶ Consider border to border run segments;
- ▶ Compose border to border segments;



From 2-way transducers to *H-Rat* (unary case)

We fix a transducer \mathcal{T} .

- ▶ Consider border to border run segments;
- ▶ Compose border to border segments;

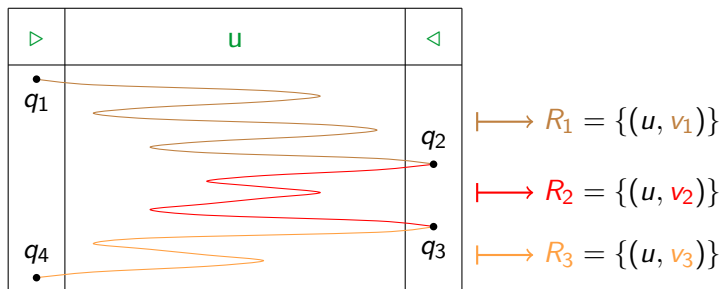


$$R_1 \oplus R_2 \oplus R_3 = \{(u, v_1 v_2 v_3)\}$$

From 2-way transducers to *H-Rat* (unary case)

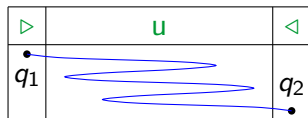
We fix a transducer \mathcal{T} .

- ▶ Consider border to border run segments;
- ▶ Compose border to border segments;
- ▶ Conclude using the closure properties of *H-Rat*.



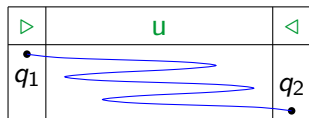
$$R_1 \oplus R_2 \oplus R_3 = \{(u, v_1 v_2 v_3)\}$$

From 2-way transducers to *H-Rat* (unary case)

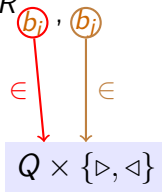


define a relation R_{b_i, b_j}

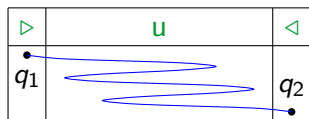
From 2-way transducers to *H-Rat* (unary case)



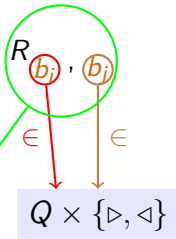
define a relation R



From 2-way transducers to *H-Rat* (unary case)



define a relation R



$$\text{HIT} = \left(\begin{array}{ccccccc}
 R_{0,0} & R_{0,1} & \cdot & \cdot & \cdot & R_{0,2} & \\
 R_{1,0} & R_{1,1} & \cdot & \cdot & \cdot & R_{1,2} & \\
 \cdot & & & & & \cdot & \\
 \cdot & & & & & \cdot & \\
 \cdot & & & & & \cdot & \\
 R_{k,0} & R_{k,1} & \cdot & \cdot & \cdot & R_{k,k} & \\
 \end{array} \right)$$

$2|Q|$ (width of matrix)
 $2|Q|$ (height of matrix)
 $R_{i,j}$ (highlighted element)

From 2-way transducers to *H-Rat* (unary case)

Second ingredient:

The behavior of \mathcal{T} is given by the matrix HIT^{H^*} .

From 2-way transducers to H -Rat (unary case)

Second ingredient:

The behavior of \mathcal{T} is given by the matrix HIT^{H^*} .

Third ingredient:

Lemma

Each entry R_{b_1, b_2} of the matrix HIT is rational (constructible).

From 2-way transducers to H -Rat (unary case)

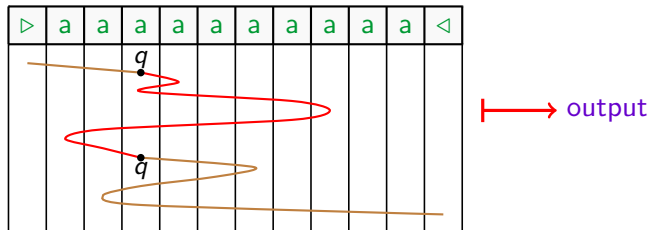
Second ingredient:

The behavior of \mathcal{T} is given by the matrix HIT^{H^*} .

Third ingredient:

Lemma

Each entry R_{b_1, b_2} of the matrix HIT is rational (constructible).



From 2-way transducers to H -Rat (unary case)

Second ingredient:

The behavior of \mathcal{T} is given by the matrix HIT^{H^*} .

Third ingredient:

Lemma

Each entry R_{b_1, b_2} of the matrix HIT is rational (constructible).

By closure property:

Corollary

Each entry of HIT^{H^*} is in H -Rat.

From 2-way transducers to *H-Rat* (unary case)

Second ingredient:

The behavior of \mathcal{T} is given by the matrix HIT^{H^*} .

Third ingredient:

Lemma

Each entry R_{b_1, b_2} of the matrix HIT is *rational* (*constructible*).

By closure property:

Corollary

Each entry of HIT^{H^*} is in *H-Rat*.

Remark

The relation accepted by \mathcal{T} is a union of entries of HIT^{H^*} .

From 2-way transducers to $H\text{-Rat}$ (unary case)

Second ingredient:

The behavior of \mathcal{T} is given by the matrix HIT^{H^*} .

Third ingredient:

Lemma

Each entry R_{b_1, b_2} of the matrix HIT is rational (constructible).

By closure property:

Corollary

Each entry of HIT^{H^*} is in $H\text{-Rat}$.

Remark

The relation accepted by \mathcal{T} is a union of entries of HIT^{H^*} .

Corollary

accepted by 2-way transducers \subseteq $H\text{-Rat}$

Conclusion

Theorem

When $\Gamma = \{a\}$ and $\Sigma = \{a\}$:

2-way transducers accept exactly the H-Rat relations.

Conclusion

Theorem

When $\Gamma = \{a\}$ and $\Sigma = \{a\}$:

2-way transducers accept exactly the H-Rat relations.

From our construction follows:

- ▶ 2-way transducers can be made **sweeping**.

Conclusion

Theorem

When $\Gamma = \{a\}$ and $\Sigma = \{a\}$:

2-way transducers accept exactly the H-Rat relations.

From our construction follows:

- ▶ 2-way transducers can be made **sweeping**.

With only $\Gamma = \{a\}$:

- ▶ 2-way $\left. \begin{array}{l} \text{deterministic} \\ \text{unambiguous} \\ \text{functional} \end{array} \right\}$ accept rational relations.

Conclusion

Theorem

When $\Gamma = \{a\}$ and $\Sigma = \{a\}$:

2-way transducers accept exactly the H-Rat relations.

From our construction follows:

- ▶ 2-way transducers can be made **sweeping**.

With only $\Gamma = \{a\}$:

- ▶ 2-way $\left\{ \begin{array}{l} \text{deterministic} \\ \text{unambiguous} \\ \text{functional} \end{array} \right\}$ accept rational relations.

- ▶ 2-way transducers are **uniformizable** by 1-way transducers.

Conclusion

Theorem

When $\Gamma = \{a\}$ and $\Sigma = \{a\}$:

2-way transducers accept exactly the H-Rat relations.

From our construction follows:

- ▶ 2-way transducers can be made **sweeping**.

With only $\Gamma = \{a\}$:

- ▶ 2-way $\left\{ \begin{array}{l} \text{deterministic} \\ \text{unambiguous} \\ \text{functional} \end{array} \right\}$ accept rational relations.

- ▶ 2-way transducers are **uniformizable** by 1-way transducers.

Every thing is **constructible**.

Conclusion

Theorem

When $\Gamma = \{a\}$ and $\Sigma = \{a\}$:

2-way transducers accept exactly the H-Rat relations.

From our construction follows:

- ▶ 2-way transducers can be made **sweeping**.

With only $\Gamma = \{a\}$:

- ▶ 2-way $\left\{ \begin{array}{l} \text{deterministic} \\ \text{unambiguous} \\ \text{functional} \end{array} \right\}$ accept rational relations.

- ▶ 2-way transducers are **uniformizable** by 1-way transducers.

Every thing is **constructible**.